SmallSat Precision Navigation With Low-Cost MEMS IMU Swarms



Completed Technology Project (2013 - 2014)

Project Introduction

Small satellite missions are characterized by tight constraints on cost, mass, power, and volume that make them unable to fly high performance inertial measurement units (IMUs) required for orbital missions demanding precise orientation and positioning. Instead, small satellite missions typically fly low-cost MEMS (micro-electro-mechanical system) IMUs. Unfortunately, the performance characteristics of these MEMS IMUs make them ineffectual in many spaceflight applications when employed in a single IMU system configuration. This study will create an 'effective' tactical-grade IMU, thus allowing future small satellites to tackle

Anticipated Benefits

This results of this project will create an Effective tactical-grade IMU, allowing future small satellites to tackle more aggressive missions.

Primary U.S. Work Locations and Key Partners





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Small Spacecraft Technology

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Organizations Performing Work	Role	Туре	Location
	Lead	NASA	Houston,
	Organization	Center	Texas
Marquette	Supporting	Academia	Milwaukee,
University	Organization		Wisconsin
West Virginia	Supporting	Academia	Morgantown,
University	Organization		West Virginia

Primary U.S. Work Locations			
Texas	West Virginia		
Wisconsin			

Project Website:

https://www.nasa.gov/directorates/spacetech/home/index.html

Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Center / Facility:

Johnson Space Center (JSC)

Responsible Program:

Small Spacecraft Technology

Project Management

Program Director:

Christopher E Baker

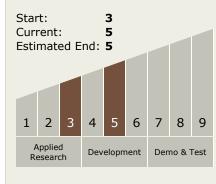
Program Manager:

Roger Hunter

Principal Investigator:

John Christian

Technology Maturity (TRL)





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Technology Areas

Other/Cross-cutting:

- TX17 Guidance, Navigation, and Control (GN&C)
 - □ TX17.2 Navigation Technologies
 - ☐ TX17.2.3 Navigation Sensors

Target Destinations

Earth, Foundational Knowledge

